

BOOK: Linear Algebra: Theory, Intuition, Code

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CHAPTER: Matrix multiplications (chapter 6)

```
In [2]: ## import Libraries for the entire chapter  
import numpy as np
```

Section 6.1, code block 6.1 -- "tandard" matrix multiplication

MOLTIPLICAZIONE "Standard" delle Matrici 6.1

Indichiamo con AB = moltiplicazione standard delle Matrici

$$A = \begin{pmatrix} 1 & 0 & 2 \\ 0 & 3 & -1 \end{pmatrix} \quad B = \begin{pmatrix} 4 & 1 \\ -2 & 2 \\ 0 & 3 \end{pmatrix}$$

AB

```
In [7]: import numpy as np  
# two matrices  
#M1 = np.random.randn(4,3)  
M1 = np.random.randint(5,size=(2,3))  
#M2 = np.random.randn(3,5)  
M2 = np.random.randint(5,size=(3,4))  
print(M1)  
print(' ')  
print(M2)  
print(' ')  
  
# and their product  
C = M1 @ M2  
print(C)
```

```
[[2 2 2]  
 [1 2 0]]
```

```
[[3 3 2 4]  
 [3 0 1 2]  
 [0 1 0 4]]
```

```
[[12 8 6 20]  
 [ 9 3 4 8]]
```

TERMINOLOGIA

Il prodotto non è commutativo $\mathbf{AB} \neq \mathbf{BA}$

ECCEZIONE: $\mathbf{AI} = \mathbf{IA}$

```
'A times B'  
'A left-multiplies B'  
'A pre-multiplies B'  
'B right-multiplies A'  
'B post-multiplies A'
```

Section 6.2, code block 6.3 -- Non-commutivity of matrix multiplication

```
In [15]: #A = np.random.randn(2,2)  
#B = np.random.randn(2,2)  
A = np.random.randint(5,size=(2,2))  
B = np.random.randint(5,size=(2,2))  
# notice that C1 != C2  
C1 = A@B  
C2 = B@A  
print(A, ' = A')  
print(' ')  
print(B, ' = B')  
print(' ')  
print(C1, ' = AB')  
print(' ')  
print(C2, ' = BA')
```

```
[[1 1]  
 [3 4]] = A
```

```
[[1 2]  
 [4 3]] = B
```

```
[[ 5  5]  
 [19 18]] = AB
```

```
[[ 7  9]  
 [13 16]] = BA
```

Section 6.3, Matrix multiplication with a diagonal matrix

MOLTIPLICAZIONI e EQUAZIONI

MOLTIPLICAZIONE di una MATRICE con una MATRICE DIAGONALE

$$\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} = \begin{bmatrix} 1a & 2a & 3a \\ 4b & 5b & 6b \\ 7c & 8c & 9c \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} = \begin{bmatrix} 1a & 2b & 3c \\ 4a & 5b & 6c \\ 7a & 8b & 9c \end{bmatrix}$$

$$\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \begin{bmatrix} d & 0 & 0 \\ 0 & e & 0 \\ 0 & 0 & f \end{bmatrix} = \begin{bmatrix} ad & 0 & 0 \\ 0 & be & 0 \\ 0 & 0 & cf \end{bmatrix}$$

The LIVE EVIL rule: Reverse matrix order

$$(\mathbf{A} \dots \mathbf{B})^T = \mathbf{B}^T \dots \mathbf{A}^T \quad (6.7)$$

Section 6.4, LIVE EVIL! (a.k.a. order of operations)

LIVE-EVIL si applica anche all'inversa di una matrice

Section 6.5, Matrix-vector multiplication

PRODOTTO MATRICE-VETTORE

Section 6.8, code block 6.5

Symmetric matrix times a vector

$$\text{if } \mathbf{A} = \mathbf{A}^T \text{ then } \mathbf{A}\mathbf{b} = (\mathbf{b}^T\mathbf{A})^T \quad (6.8)$$

```
In [ ]: M1 = np.random.randn(4,3)
M2 = np.random.randn(4,3)
C = M1 * M2 # note the * instead of @
```

Section 6.6 -- Creating symmetric matrices

$$\mathbf{C} = \frac{1}{2}(\mathbf{A}^T + \mathbf{A}) \quad (6.9)$$

Section 6.7, Multiplication of two symmetric matrices

in general it is not a symmetric operation

Section 6.8, Element-wise (Hadamard) multiplication

$$\mathbf{C} = \mathbf{A} \odot \mathbf{B} \quad (6.19)$$

The formal definition of Hadamard multiplication is

Hadamard (element-wise) multiplication	
$c_{i,j} = a_{i,j} \times b_{i,j}$	(6.20)

Section 6.9, code block 6.7 -- Creating symmetric matrices

```
In [17]: A = np.array([ [1,2,3],[4,5,6] ])
B = A.flatten(order='F')
print(A)
print(' ')
print(B)
```

```
[[1 2 3]
 [4 5 6]]
```

```
[1 4 2 5 3 6]
```

Section 6.9, code block 6.9 -- Frobenius dot product

FROBENIUS PRODUCT

Frobenius dot product as the trace of $\mathbf{A}^T \mathbf{B}$	
$\langle \mathbf{A}, \mathbf{B} \rangle_F = \text{tr}(\mathbf{A}^T \mathbf{B})$	(6.23)

The code below shows the trace-transpose trick for computing the Frobenius product

Frobenius matrix norm	
$\ \mathbf{A}\ _F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n (a_{i,j})^2}$	(6.24)

Euclidean distance between two matrices	
$\ \mathbf{A} - \mathbf{B}\ _F = \sqrt{\sum_{i,j} (a_{i,j} - b_{i,j})^2}$	(6.25)

```
In [3]: A = np.random.randint(5, size=(4,3))
B = np.random.randint(5, size=(4,3))

# the transpose-trace trick for the Frobenius dot product
C = A.T@B
f = np.trace(C)
print(A)
print(' ')
print(B)
print(' ')
print(C)
print(' ')
print(f)
```

```
[[4 1 2]
 [3 4 0]
 [1 4 0]
 [4 2 2]]
```

```
[[1 4 0]
 [1 1 0]
 [1 1 0]
 [2 1 1]]
```

```
[[16 24 4]
 [13 14 2]
 [ 6 10 2]]
```

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Section 6.10, Matrix norms

Section 6.10, Codeblock 6.11 -- Frobenius norm

```
In [5]: A = np.random.randint(5,size=(4,3))
        B = np.linalg.norm(A,'fro')
        # questa e La somma dei quadrati di ogni elemento, quindi La Loro radice quadrata
        print(A)
        print(' ')
        print(B)
```

```
[[4 3 2]
 [3 4 0]
 [0 3 1]
 [1 0 2]]
```

8.306623862918075

Section 6.11, From a square matrix A, we get a skew-symmetric matrix K, and the symmetric one L

```
In [41]: # MATRICE GENERICA
        A1 = ([[1, 2, 3],[4, 5, 6],[7, 8, 9]])
        A = Aa = np.array(A1)
        B = A.transpose()
        K = (A-B)/2
        #print(K)
        L = (A+K)
        #print(L)
        K_frobenius_norm = pow(np.linalg.norm(K),2)
        A_frobenius_norm = pow(np.linalg.norm(A),2)
        A_sigma = int(K_frobenius_norm/A_frobenius_norm*1000)/1000
        print('Asymmetry index of a generic matrix A = ',A_sigma)

        A1 = K
        B1 = K.transpose()
        K1 = (A1-B1)/2
        K1_frobenius_norm = pow(np.linalg.norm(K1),2)
        A1_frobenius_norm = pow(np.linalg.norm(A1),2)
        A1_sigma = K1_frobenius_norm/A1_frobenius_norm
        #print(K1)
        print('Asymmetry index of a skew-matrix A1 = ',A1_sigma)
```

```

A2 = L
B2 = L.transpose()
K2 = (A2-B2)/2
K2_frobenius_norm = pow(np.linalg.norm(K2),2)
A2_frobenius_norm = pow(np.linalg.norm(A2),2)
A2_sigma = K2_frobenius_norm/A2_frobenius_norm
#print(K1)
print('Asymmetry index of a symmetric matrix A2 = ',A2_sigma)

```

Asymmetry index of a generic matrix A = 0.042
Asymmetry index of a skew-matrix A1 = 1.0
Asymmetry index of a symmetric matrix A2 = 0.0

Section 6.12, What about matrix division?

Section 6.13, Exercises

Section 6.14, Answers

Section 6.15, Code challenges

Section 6.16 - Code block 6.13 -- very small numbers should be considered as zeros

```

In [11]: # two matrices
#A = np.random.randn(2,4)
#B = np.random.randn(4,3)
A = np.random.randint(5,size=(2,4))
B = np.random.randint(5,size=(4,3))
print(A@B)

# initialize product
C1 = np.zeros((2,3))

# sum over columns
for i in range(4):
    C1 += np.outer(A[:,i],B[i,:])
print(C1)
# show equality
D = C1 - A@B
print(D)

```

```

[[27 19 27]
 [17 13 16]]
[[27. 19. 27.]
 [17. 13. 16.]]
[[0. 0. 0.]
 [0. 0. 0.]]

```

Section 6.15, code block 6.15 -- The diagonals of the two product matrices are the same.

```

In [44]: # a diagonal matrix and a full one
D = np.diag(np.arange(1,5))

```

```

#A = np.random.randn(4,4)
A = np.random.randint(5,size=(4,4))
#print(D) # matrice diagonale
#print(A) # matrice 4x4

# two kinds of products
C1 = D*A # una matrice diagonale moltiplicata per A
C2 = D@A # prodotto standard delle due matrici
#print(C1)
#print(C2)

# are they the same?
print(np.diag(C1))
print(np.diag(C2))

```

```

[1 8 3 8]
[1 8 3 8]

```

Section 6.15, code block 6.17 -- Square root of a special matrix

La radice quadrata funziona perché A è diagonale. Il motivo per cui funziona è lo stesso per cui funziona $x = (\sqrt{x})^2$, per $x \geq 0$.

```

In [42]: # diagonal matrix
A = np.diag(np.random.rand(3))
#print(A)
# two symmetric matrices
C1 = (A.T+A)/2
C2 = A.T@A
#print(C1) # C1 e C2 sono uguali
#print(C2)
# are they the same?
D = C1-np.sqrt(C2)
print(D)

```

```

[[0. 0. 0.]
 [0. 0. 0.]
 [0. 0. 0.]]

```

Section 6.15, code block 6.19 -- With this method the "inequality" is always > 0

```

In [43]: # a matrix and a vector (walk into a bar...)
m = 5
A = np.random.randn(m,m)
v = np.random.randn(m)

# the two sides of the equation
LHS = np.linalg.norm(A@v)
RHS = np.linalg.norm(A,ord='fro') * np.linalg.norm(v)
#print(LHS)
#print(RHS)
# should always be positive
D = RHS-LHS
print(D)

```

4.476710510613195

In []: